## 

PHOTOELECTRIC ROTARY ENCODER

AN

The Encoder-AN is a high-resolution, singleturn absolute encoder with a 22 Bit BiSS C interface. The encoder consists of several optical reflectance sensors arranged at an angle of 180 degrees to each other.

This allows to eliminate mechanical errors in the application, such as the runout of the measured shaft, by using subsequent electronics.


## MECHANICAL DATA

| Permissible axial motion of measured shaft | 0.03 mm | Permissible vibration (55 to 2000 Hz$)$ | $\leq 100 \mathrm{~m} / \mathrm{s}^{2}$ |
| :--- | :---: | :--- | :--- |
| Permissible radial runout of measured shaft | 0.03 mm | Permissible shock (11 ms) | $\leq 200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Moment of inertia of rotor | $<30 \times 10^{-6} \mathrm{kgm}^{2}$ | Operating temperature | $-40-1000^{\circ} \mathrm{C}$ |
| Maximum weight | 0.05 kg | Storage temperature | $-40-100^{\circ} \mathrm{C}$ |
| Type of protection (IEC 529) | $1 P 00$ |  |  |
| Maximum humidity <br> (non-condensing) | $98 \%$ |  |  |

## ELECTRICAL DATA

| Resolution | 22 bit | Monoflop time | timeout $+T / 2$ us |
| :---: | :---: | :---: | :---: |
| Output code | Binary | Rise and fall time | 4-15ns |
| Data interface | Biss-c | Analog signals | $\sim 1 \mathrm{Vpp}$ (1024ppr) |
| Accuracy | $\leq \pm 100{ }^{\prime \prime}$ | Cutoff frequency | <240 kHz |
| Supply voltage | $+5 \mathrm{~V} \pm 5 \%$; | Amplitude output voltage | 0.6-1.2V |
| Supply current | 80-220 mA | Maximum output current | 22 mA |
| Start up time | 13 ms | Lightsource | LED |
| Scan ratio of $T$ | 40-60\% |  |  |

## INSTALLATION ERROR

Due to dimensional and form error of the customer's shaft as well as its radial runout and fit tolerances with encoder disc / hub assembly the unwanted runout of the circular scale appears and leads to increased angle measurement error. The following installation error $\Delta \Phi$ relationship between the radial runout $\mathbf{r}$ and the mean diameter $\mathbf{D}$ of the graduation is expressed:

## $\Delta \Phi= \pm 412 \times 0.5 \mathrm{r} / \mathrm{D} \quad \mathrm{D}=65,26 \mathrm{~mm}$

## INTERFACE

## DATA TRANSFER BISS-C


The position data increases when the shaft rotates in the direction shown in the drawing

| DESCRIPTION | DATA |
| :---: | :---: |
| $T_{\text {mamas }}$ | 0.075 us -24 us |

TYPICAL OPERATING CIRCUIT FOR BISS-C


This is just one example of a tailor made encoder kit. For other mechanical, electrical configurations or different interface
options please contact us directly: sales@precizika.com

